Calculations of High-Lift Wing-Body Configuration with k-ω Model Variants

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Overall Objective

- To develop physics based improvements to RANS and multi-resolution PANS models for highly separated aerodynamic flows
 - Start from fundamental first principles
 - Develop all models from a single unified framework

Background and Motivation

- PANS proven in bluff body flows (FLUENT, FIRE, etc)
- Near-wall low Re PANS yet to be developed
 - Requires development physics based on low Re RANS models
- Many low Re RANS models are ad hoc and can not be directly applied to PANS
- Similar effort underway in Sweden (Peng et. al.)

Models Tested on Wing-Body for Workshop

- SA
- k-ε
- SST
- VLES
- RSM
- k-ω
 - Wilcox 1988 k-ω[§] (Baseline)
 - Wilcox 1988 k-ω with M1 Modification (M1)
 - Wilcox 1988 k-ω with M2 Modification (M2)
 - Wilcox 2006 k-ω¶

[§] Wilcox, D. C., "Reassessment of the Scale-Determining Equation for Advanced Turbulence Models," AIAA Journal, Vol.26, No. 11, 1988, pp. 1299-1310.

[¶] Wilcox, D. C., Turbulence Modeling for CFD, 3rd Ed., DCW Industries, 2006.

Outline

- Methodology of M1 and M2 Modifications
- Computational Setup
- Studies
 - P/ε Limiter Study
 - k-ω Model Variants Comparison with SA
 - Grid Convergence Study
 - Detailed Comparison of Baseline, M1, and SA Models
- Conclusions

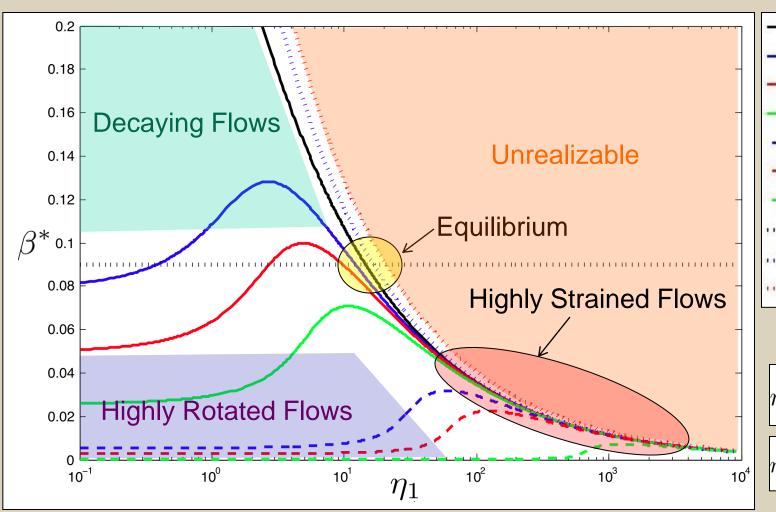
Standard Approach: Constant β^* (C_μ)

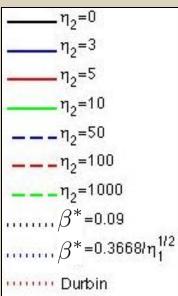
- Constant β* valid when
 - Turbulence is near equilibrium

Not Applicable When

- Flow is very rapidly strained
 - S>>ω
 - Mean strain >> fluctuating strain
 - Turbulence is elastic rather than viscous
 - $-\beta^* = \beta^*(S,\omega)$
- Rotation Dominated Flows
 - W>>S
 - $\beta^* = \beta^*(S, W, \omega)$

General β* Behavior





$$\eta_1 = \frac{k^2}{\varepsilon^2} S_{ij} S_{ij}$$

$$\eta_2 = \frac{k^2}{\varepsilon^2} W_{ij} W_{ij}$$

ARSM Based Variable β* Model

Full ARSM:
$$b_{ij} = G_1 S_{ij}^* + G_2 (S_{ij}^* W_{kj}^* - W_{ik}^* S_{kj}^*) + G_3 \left(S_{ik}^* S_{kj}^* - \frac{1}{3} S_{mn}^* S_{mn}^* \delta_{ij} \right)$$

Linear Truncated ARSM: $b_{ij} = G_1 S_{ij}^*$

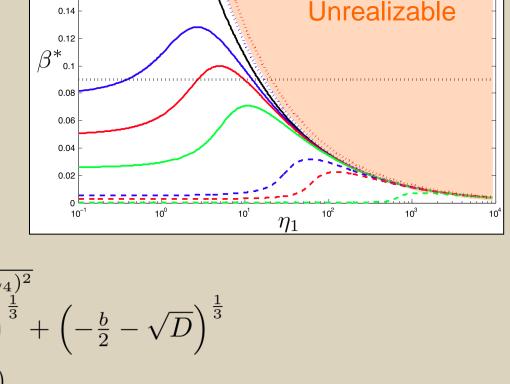
$$\overline{u_i u_j} = G_1 \frac{k^2}{\varepsilon} S_{ij} + \frac{2}{3} k \delta_{ij} \qquad \overline{u_i u_j} = -C_\mu \frac{k^2}{\varepsilon} S_{ij} + \frac{2}{3} k \delta_{ij}$$

$$-C_{\mu} = -\beta^* = G_1 = \begin{cases} \frac{L_1^0 L_2}{(L_1^0)^2 + \eta_2 (L_4)^2} \\ \frac{L_1^0 L_2}{(L_0)^2 \frac{2}{3} \eta_1 (L_3)^2 + 2\eta_2 (L_4)^2} \\ -\frac{p}{3} + \left(-\frac{b}{2} + \sqrt{D}\right)^{\frac{1}{3}} + \left(-\frac{b}{2} - \sqrt{D}\right)^{\frac{1}{3}} \\ -\frac{p}{3} + 2\sqrt{\frac{-a}{3}}\cos(\frac{\theta}{3}) \\ -\frac{p}{3} + 2\sqrt{\frac{-a}{3}}\cos(\frac{\theta}{3} + \frac{2\pi}{3}) \end{cases}$$

Girimaji, S.S., "Fully explicit and self-consistent algebraic Reynolds stress model," Theoretical and Computational FluidDynamics, Vol. 8, No. 6, 1996, pp. 387-402.

M2 Model

- M2: Valid for all strain rates and rotation rates
 - Linear coefficient from ARSM, $\beta^* = \beta^* (W_{ii}, S_{ii})$



0.18

0.16

0.14

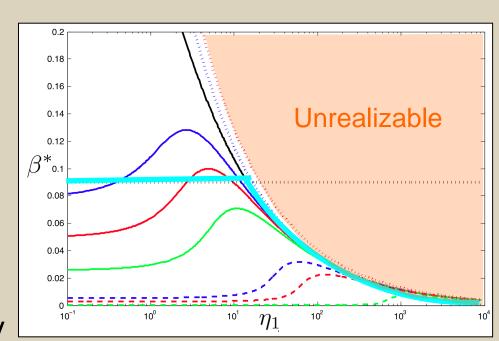
$$-\beta^* = G_1 = \begin{cases} \frac{L_1^0 L_2}{(L_1^0)^2 + \eta_2 (L_4)^2} \\ \frac{L_1^0 L_2}{(L_0)^2 \frac{2}{3} \eta_1 (L_3)^2 + 2\eta_2 (L_4)^2} \\ -\frac{p}{3} + \left(-\frac{b}{2} + \sqrt{D}\right)^{\frac{1}{3}} + \left(-\frac{b}{2} - \sqrt{D}\right)^{\frac{1}{3}} \\ -\frac{p}{3} + 2\sqrt{\frac{-a}{3}}\cos(\frac{\theta}{3}) \\ -\frac{p}{3} + 2\sqrt{\frac{-a}{3}}\cos(\frac{\theta}{3} + \frac{2\pi}{3}) \end{cases}$$

M1 Model

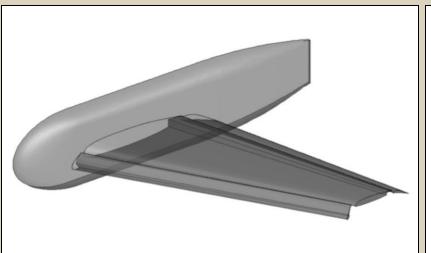
- M1: Valid for all strain rates
 - Sk/ε < 5 → β*=0.09
 - Sk/ε > 5 → ARSM Values

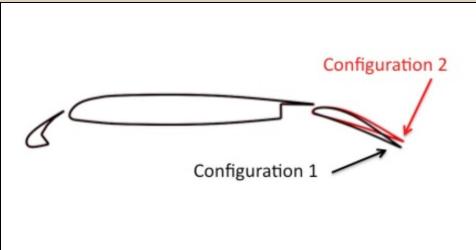
•
$$\beta^* = min\left[0.3668\left(\frac{0.09\omega}{S}\right), 0.09\right]$$

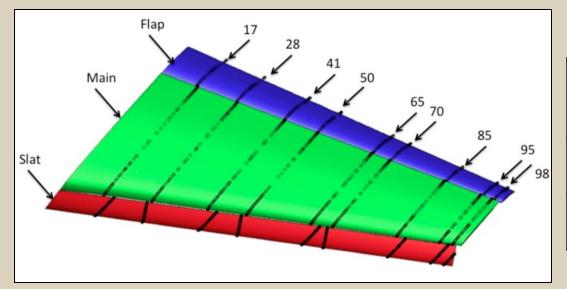
Similar to Durbin's realizability model



Computational Setup: Wing Body Geometry







Configuration	Slat	Flap
1	30 deg	25 deg
2	30 deg	20 deg

Computational Setup

- USM3D
 - tetrahedral time accurate solver
 - all simulations are steady state

Grids

- Coarse Grid: 7,237,190
- Medium Grid: 21,743,354
- Fine Grid: 62,644,381

Models

- Wicox's 1988 k-ω
- Wilcox's 1988 k-ω with M1 modification
- Wilcox's 1988 k-ω with M2 modification
- Wilcox's 2006 k-ω
- Spalart Almaras (SA)

Computational Setup

- Two Configurations Tested
 - Configuration 1
 - Slat 30 degree deflection
 - Flap 25 degree deflection
 - Configuration 2
 - Slat 30 degree deflection
 - Flap 25 degree deflection
- Angle of attacks: 6, 13, 18, 21, 28, 32, 34, 37
- M=0.2
- Re= $4.3x10^6$

Results

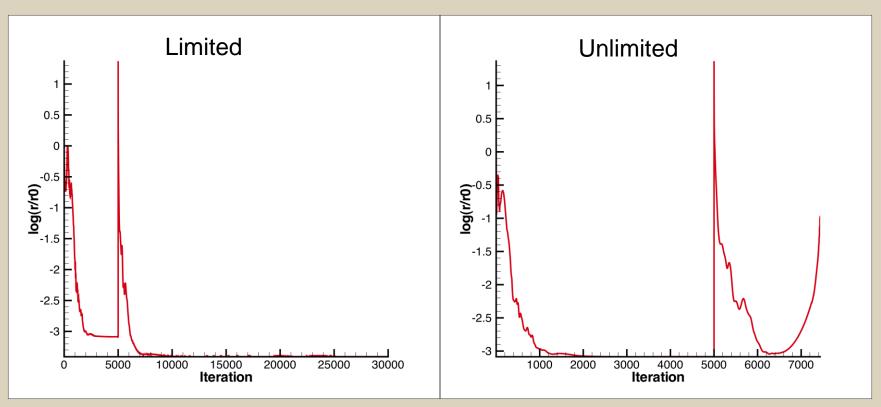
- Study 1: P/ε Limiter Study
 - Unlimited and Limit=20
- Study 2: Model Comparison Study
 - k-ω Model Variants and SA
- Study 3: Grid Convergence Study of Baseline and M1
- Study 4: Direct Comparison of Baseline, M1, and SA

Study 1: P/ε Limiter

k-ω Model Variants

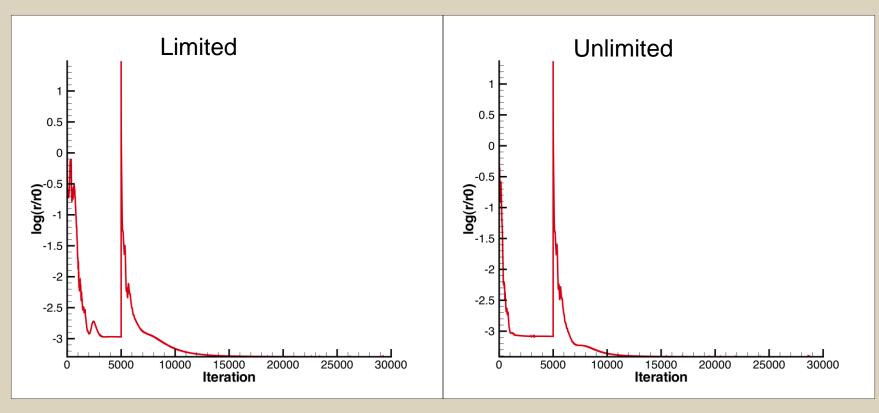
AOA 13 Configuration 1

Baseline



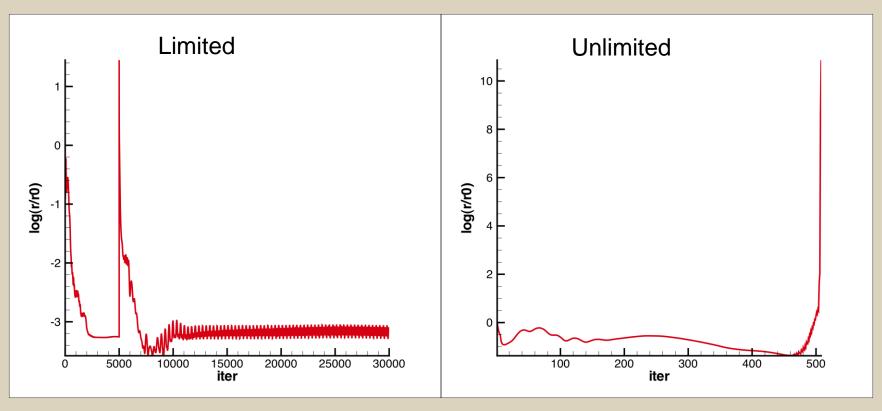
Unlimited P/ε has significant effect on convergence.

M1



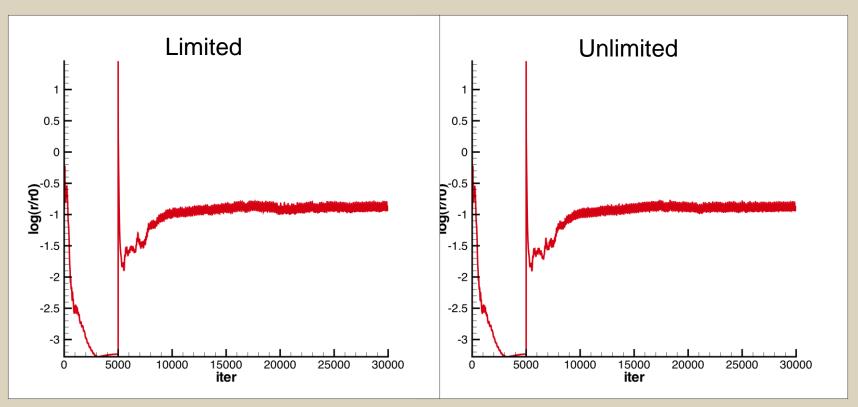
M1 is insensitive to P/ε limiter.

M2



Outstanding implementation issues are observed with M2.

Wilcox 2006

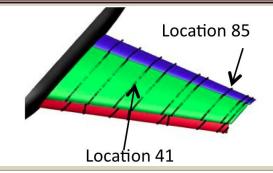


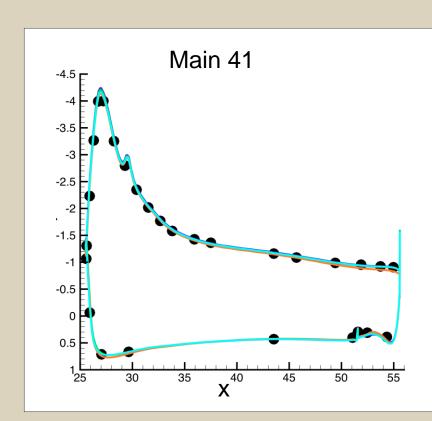
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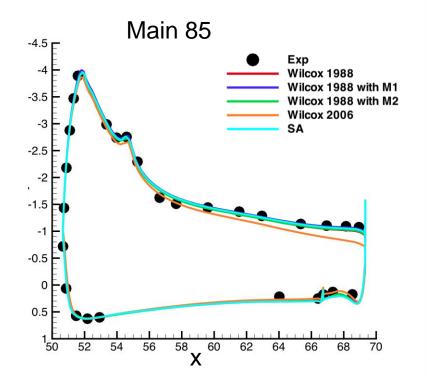
Study 2: Model Comparison Studies

C_p Distribution at AOA 13 Configuration 1

AOA 13

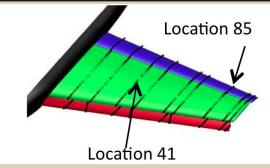


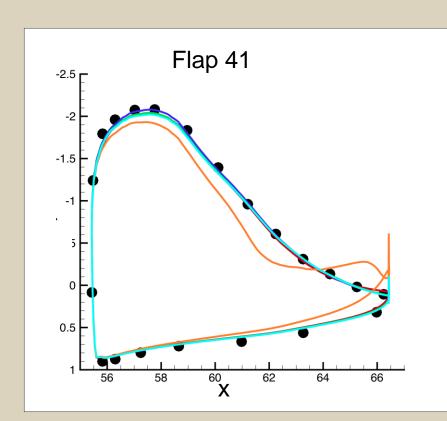


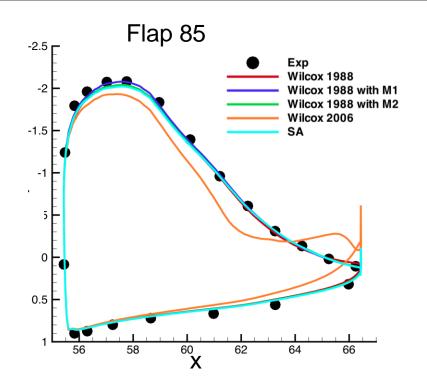


All models are comparable with Wilcox 2006 performing slightly worse.

AOA 13







Wilcox 2006 performs poorly.

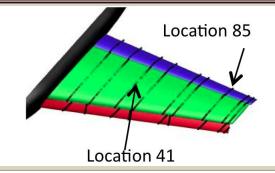
M2 needs to be further investigated.

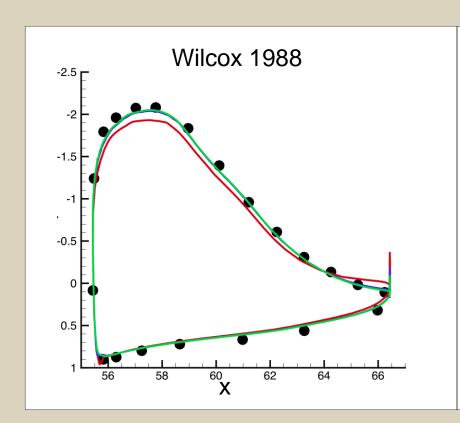
Study 3: Grid Convergence for Baseline and M1

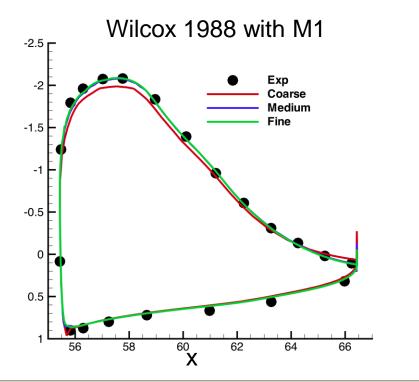
C_p Distribution at AOA 13

Configuration 1

Flap 41 AOA = 13 degrees

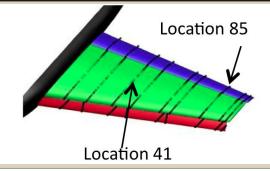


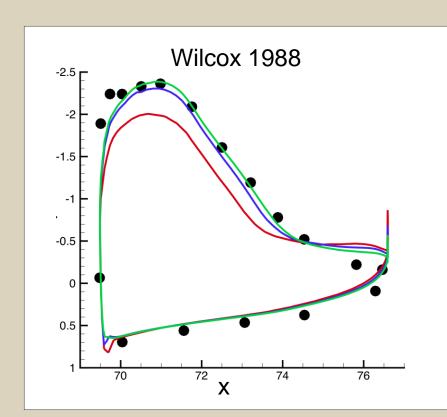


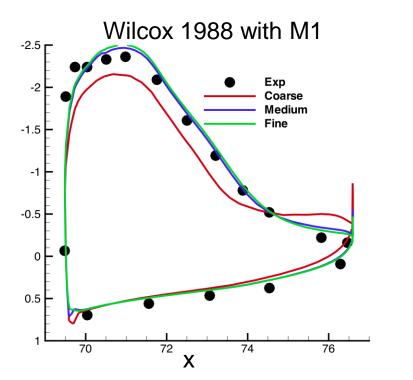


Grids convergence for each model at AOA 13.

Flap 85 AOA = 13 degrees







Convergence between medium and fine grids is better for M1.

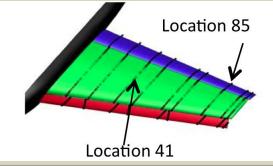
Study 4: Comparisons of Baseline, M1, and SA

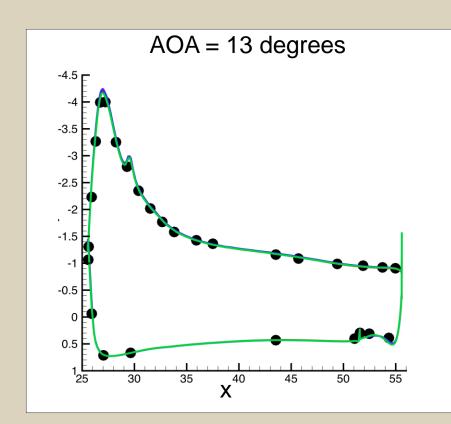
C_p Distribution at AOA 13 & 28

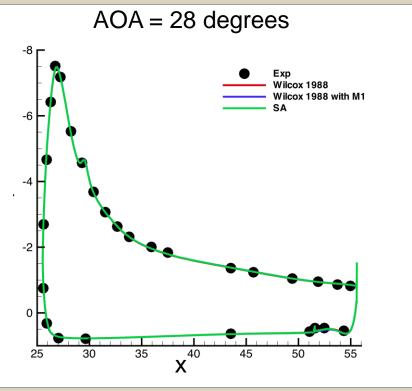
Configuration 1

Force and Moment Plots

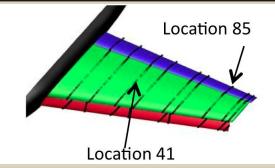
Configurations 1 & 2

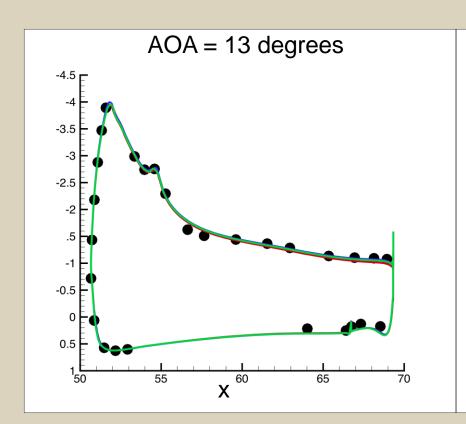


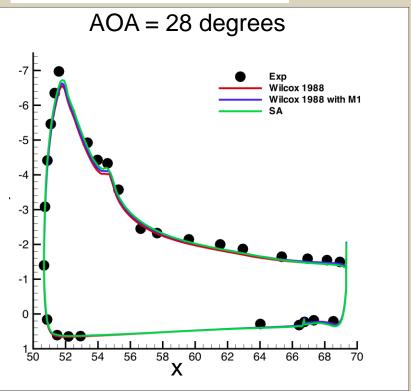




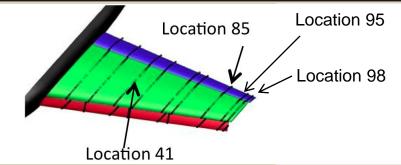
Models perform equally well.

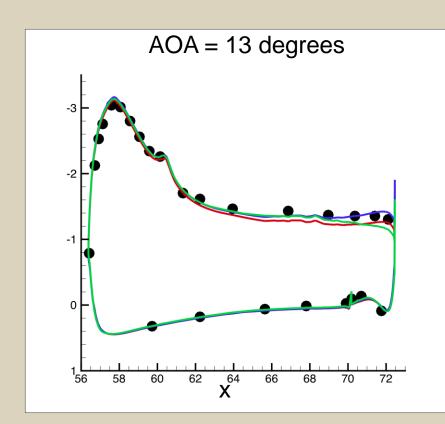


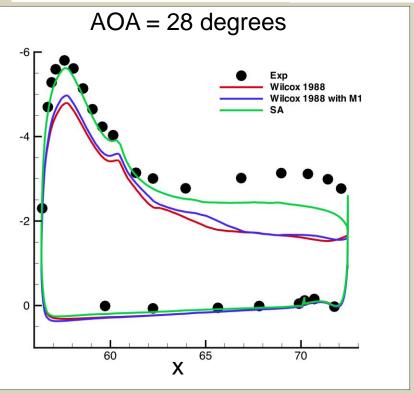




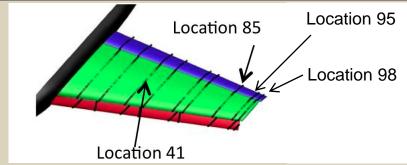
Models perform equally well.

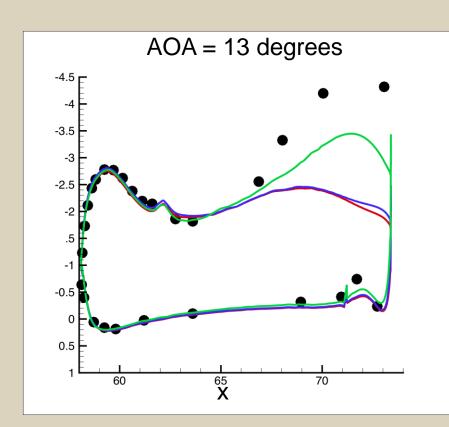


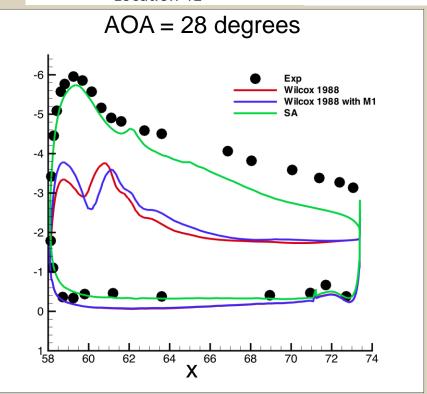




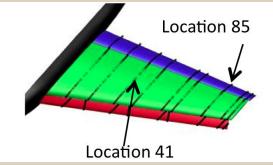
SA performs best. M1 performs marginally better than Wilcox 1988.

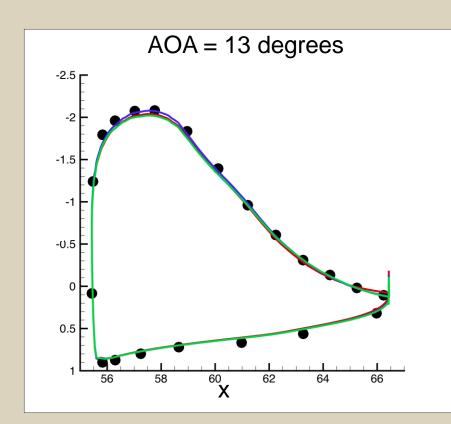


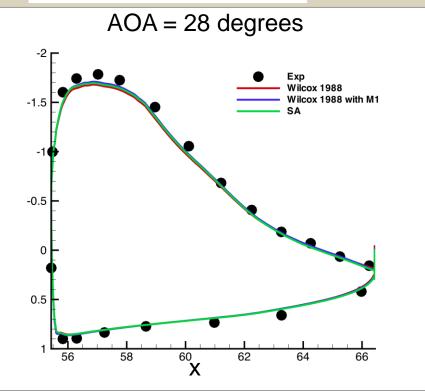




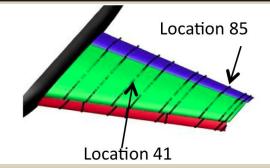
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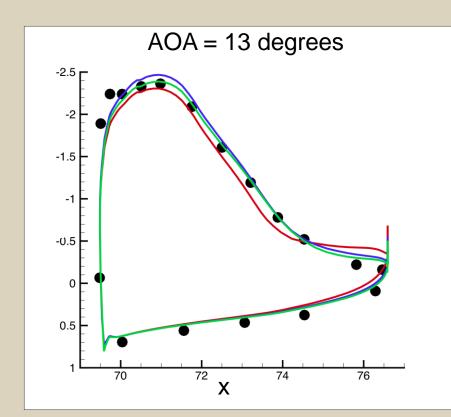


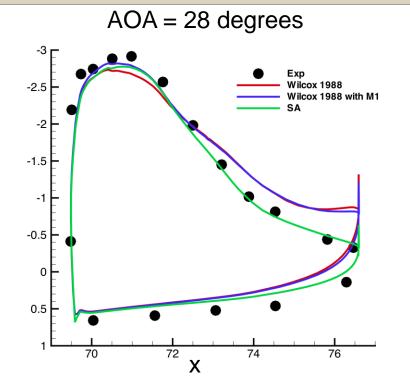




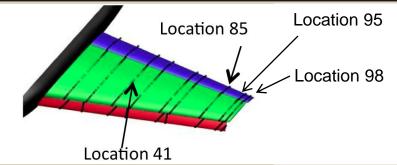
Models perform equally well.

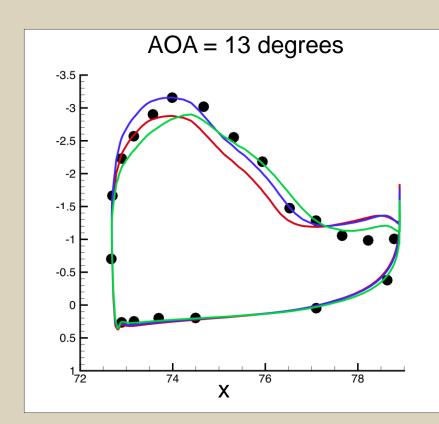


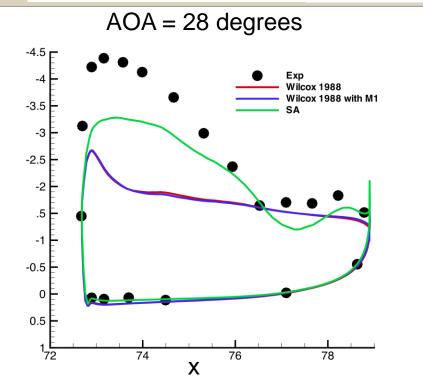




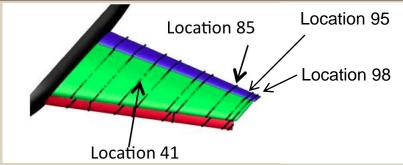
M1 comparable to SA at AOA=13 degrees. SA best at AOA=28 degrees.

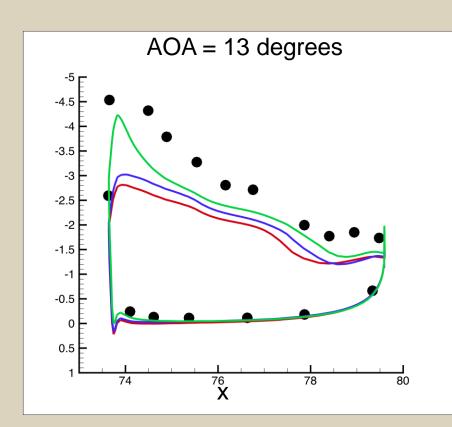


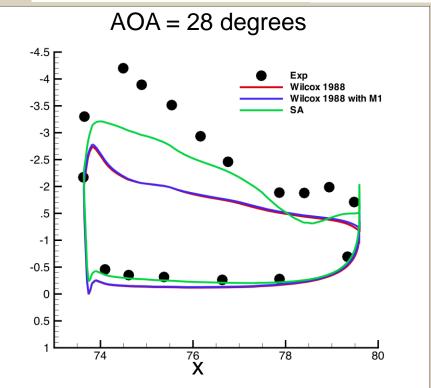




SA and M1 perform marginally better than Wilcox 1988 at AOA=13.

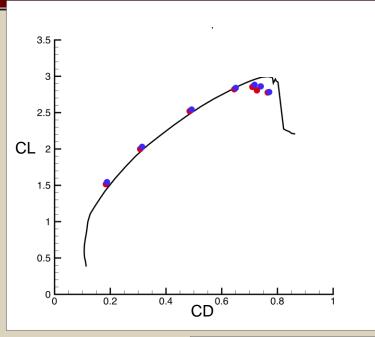


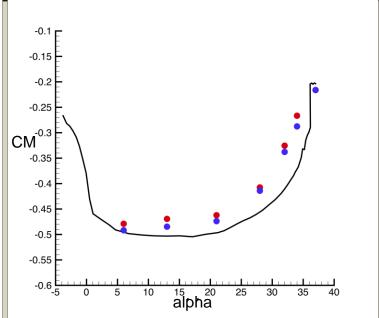




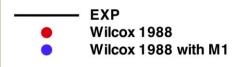
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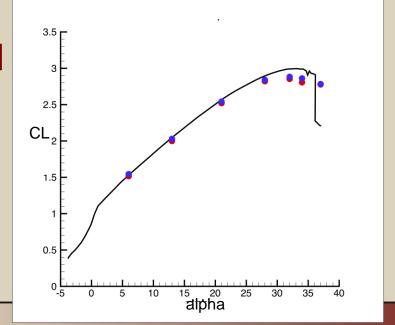
TEXAS A&M★ENGINEERING



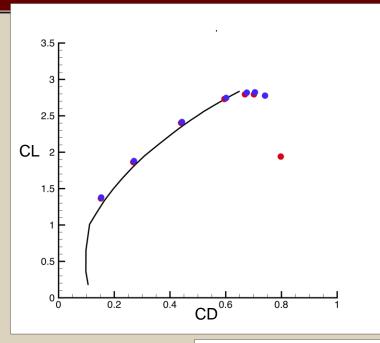


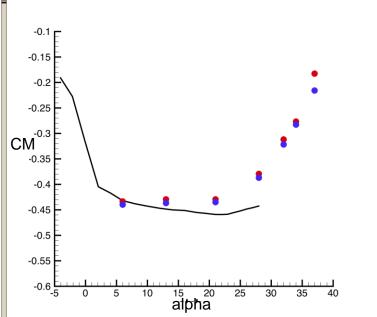
Configuration 1





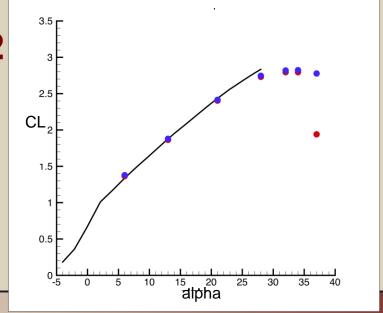
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Configuration 2

EXPWilcox 1988Wilcox 1988 with M1



Conclusions

- k-ω model variants tested on wing-body
- Wilcox 2006 found to be unsuitable for this case
 - Developed for jet flows
- M2 model needs further investigation into appropriate implementation
 - Implicit implementation rather than explicit
- M1 is more robust than Wilcox 1988
 - Required no limiter
 - Performed slightly better
- Future Work
 - More careful implementation of M2 model

Questions?